# mipi<sup>®</sup> DEVCON

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Powering Imaging Applications with MIPI CSI-2<sup>™</sup>

2017 MIPI ALLIANCE DEVELOPERS CONFERENCE

#### HSINCHU CITY, TAIWAN MIPI.ORG/DEVCON



### Agenda

- Implementation of MIPI interfaces in mobile applications and beyond
- Advantages of implementing MIPI camera and sensor specifications
- Meeting reliability requirements of automotive applications
- Summary



### **MIPI Specifications in New Applications**



**Synopsys** 



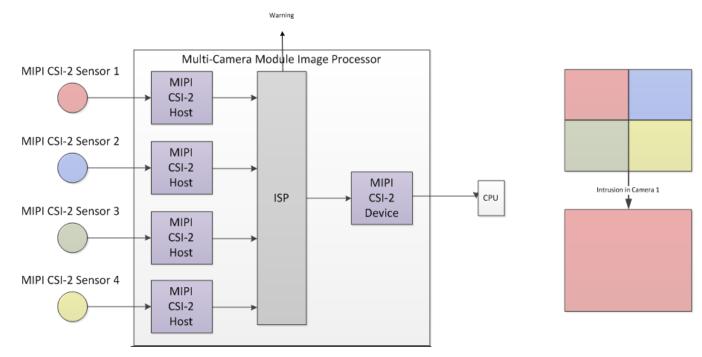
### **Industrial, Surveillance Applications**



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### **Example: Multi-Image Sensor Surveillance**



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# **Advanced Driver Assistance Systems (ADAS)**

- Passive ADAS
  - Back-up, side mirror, surround

view camera



- Deck surroundings for safely
- Distance alert system

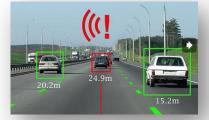


- Active ADAS
  - Back-up camera with ID &

braking



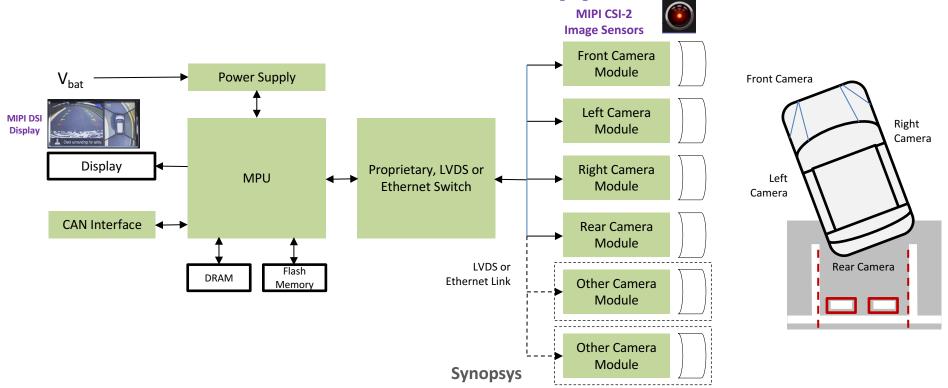
Collision avoidance



**Synopsys** 



#### **Surround View Automotive Applications**

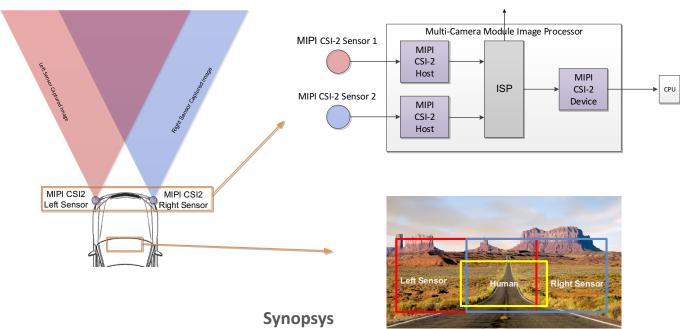




Warning

### **Surround View Automotive Applications**

#### Pedestrian/Obstacle Detection





# **MIPI CSI-2 Specification**

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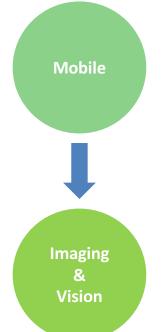
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### MIPI CSI-2 Specification – Standardizing Image Sensor Interface in Mobile and Beyond

- MIPI's first problem statement back in 2004!
  - No standard image sensor interface for Mobile
  - Interoperability challenges
  - Camera vendors had to pick and choose which devices/SoCs they developed for
  - Devices/SoCs had to pick and choose partners on the camera sensor side
  - Very difficult from a scalability point of view







### **MIPI CSI-2 Specification**

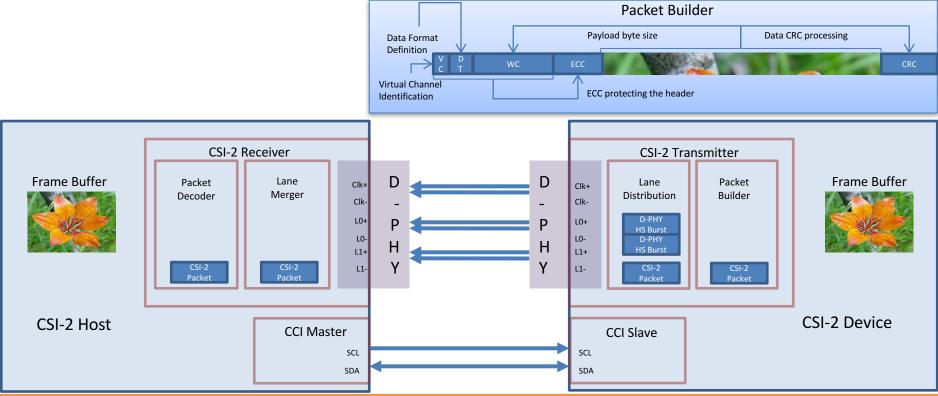
CSI-2 Specification version		<u>1.00</u> 2005	<u>1.01</u> 2011	<u>1.1</u> 2013	<u>1.2</u> 2014	<u>1.3</u> 2014	<u>2.0</u> 2017
RAW 6/7/8/10/12/14 RGB 444/555/565/666/888 YUV 420 8/10-bit YUV 422 8/10-bit		Yes	Yes	Yes	Yes	Yes	Added RAW16/20
Compression for RAW Data Types (Annex E)		-	Yes	Yes	Yes	Yes	Added 12-10-12
	Specification Version	0.58	1.00	1.1	1.2	1.2	2.1
МІРІ D-РНҮ	Speed (Gbps)	1.0	1.0	1.5	2.5	2.5	4.5 – Normal Ch. 6.5 – Short Ch.
	Number of lanes (Typically)	1 to 4	1 to 4	1 to 4	1 to 8	1 to 8	1 to 8
	PPI Interface	8-bit	8-bit	8-bit	8-bit	8-bit	8/16/32-bit
	Specification Version	-	-	-	-	1.0	1.2
МІРІ С-РНҮ	Speed (Gsym/s)	-	-	-	-	2.5	3.5
MIPI C-PHT	Number of lanes (Typically)	-	-	-	-	1 to 6	1 to 6
	PPI Interface	-	-	-	-	16-bit	16/32-bit
CCI : I2C Modes		I2C – FM (400kHz)	12C - FM	12C - FM	12C - FM	12C - FM	I2C - FM
Data Scrambling (Per-Lane)		-	-	-	-	-	Yes
Extended Virtual Channels		-	-	-	-	-	Yes
Latency Reduction and Transport Efficiency (LRTE):		-	-	-	-	-	Yes

Mobile Imaging & Vision

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### **MIPI CSI-2 Over MIPI D-PHY**





- RAW-16 and RAW-20 color depth
- Latency Reduction & Transport Efficiency (LRTE)
- Differential Pulse Code Modulation (DPCM) 12-10-12 compression
- Scrambling to reduce Power Spectral Density (PSD) emissions



• Expanded number of virtual channels from 4 to 32

#### Image Quality/HDR - Latency - Reliability - Aggregation

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- CSI-2 1v3 color depths are sufficient for Mobile. Visually, there is almost no change between RAW14 and RAW16/20.
- RAW-16 and RAW-20 color depth bring advanced vision capabilities to Automotive and Industrial applications
  - Improves image capture when the environment changes suddenly and dramatically, for example in a big change in lighting condition.

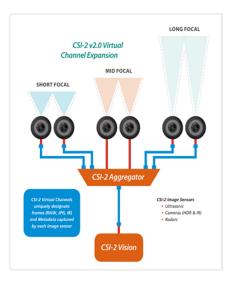




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- To accommodate the larger number of image sensors and their multiple data types
- To support multi-exposure and multi-range sensor fusion for ADAS



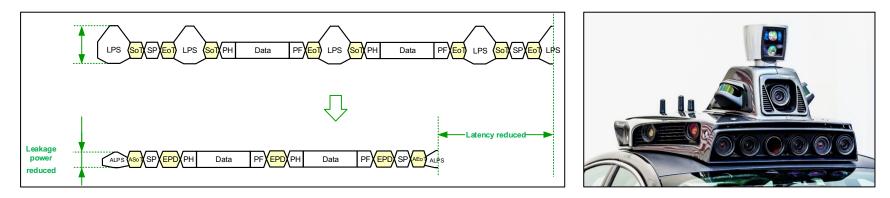
Virtual Channel 0 – Line 0	
Virtual Channel 0 – Line 1	
Virtual Channel 0 – Line 2	
Virtual Channel 0 – Line 3	
Virtual Channel 0 – Line 4	
Virtual Channel 0 – Line N	
Virtual Channel 1 – Line 0	
Virtual Channel 1 – Line 1	
Virtual Channel 1 – Line 2	
Virtual Channel 1 – Line 3	
Virtual Channel 1 – Line 4	
Virtual Channel 1 – Line M	

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Added Latency Reduction and Transport Efficiency (LRTE)

- LRTE reduces frame transport latency & leakage power due to frequent "high speed low power" transitions.
- This will enhance image sensor aggregation and multi exposure for real-time perception and decision making applications

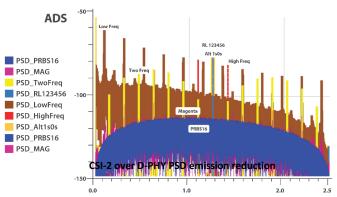


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Added scrambling and compression scheme

- Galois Field Scrambling reduces power spectral density (PSD) emissions
  - Minimizes PSD emissions from aggressor components, which are particularly beneficial when placed near sensitive receivers
- New DPCM 12-10-12 compression to further boost image quality
  - Superior SNR using reduced bandwidth PHY
  - Removes more compression artifacts when comparin with previous CSI-2 1v3 compression mode





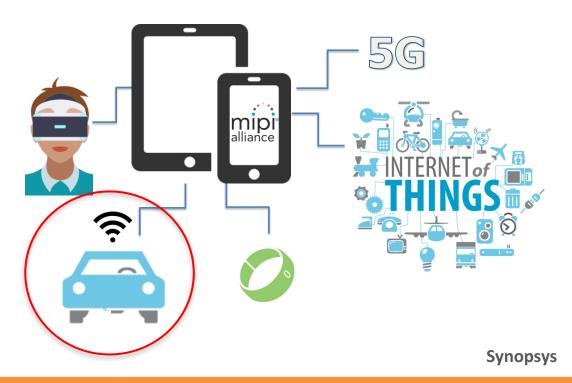
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DPCM 12-8-12 vs DPCM 12-10-12



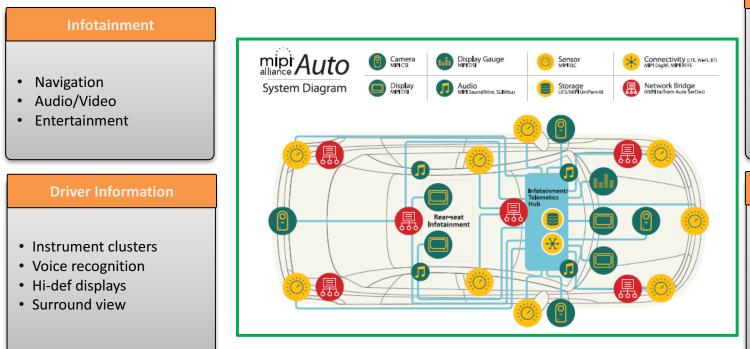
### **MIPI Specifications Beyond Mobile**

 Tackling the evolving imaging and vision applications in the automotive platform





### **MIPI Specs for Multimedia, Storage, Sensor & Wireless Connectivity in Automotive Applications**



#### Vehicle Networks & V2X

- Real time video & data network
- Gateways
- Telematics
- V2V
- V2I
- Security

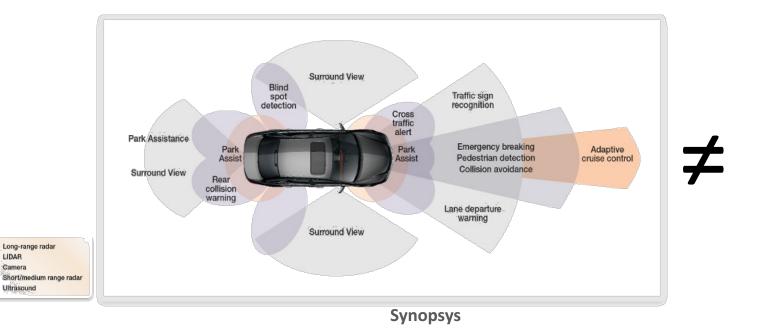
#### **Driver Assistance**

- Parking assist
- Lane departure warning & Lane keep aid
- Pedestrian detection & correction
- Automatic emergency braking



### **Safety-Critical ADAS Applications**

#### Requiring ISO 26262 certification for target ASILs





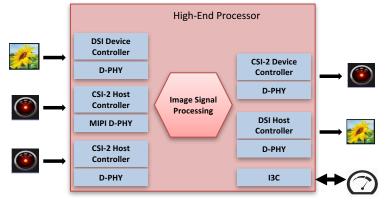
### **Key Requirements of Automotive-Grade IP**





#### DesignWare ASIL Ready ISO 26262 Certified CSI-2 IP

- Complete camera, display and sensor interface IP solutions from a single vendor
- MIPI CSI-2, MIPIJ D-PHY and MIPI I3C<sup>™</sup> protocols
  - Automotive grade1 and grade2 D-PHYs
- Enables new set of applications in automotive, AR/VR, IoT markets
  - Lowers integration risk for application processors, bridge ICs and multimedia co-processors
- Future proof IP supporting variety of speeds, proven in silicon
  - Reduces cost and power for multiple instantiations
  - Testability features enable low cost manufacturing



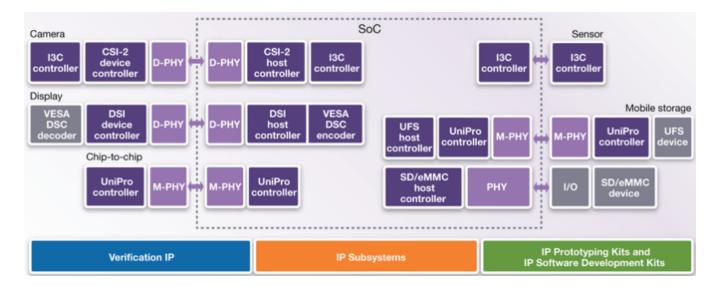


Industry's first MIPI I3C Demo

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### Synopsys® DesignWare® MIPI IP Portfolio



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